

Experience does not enhance avian avoidance of vehicles



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Background

- **>13,000** reported bird strikes with aircraft in USA in 2014
- **>\$900 million** in damages in USA each year



American
white pelican

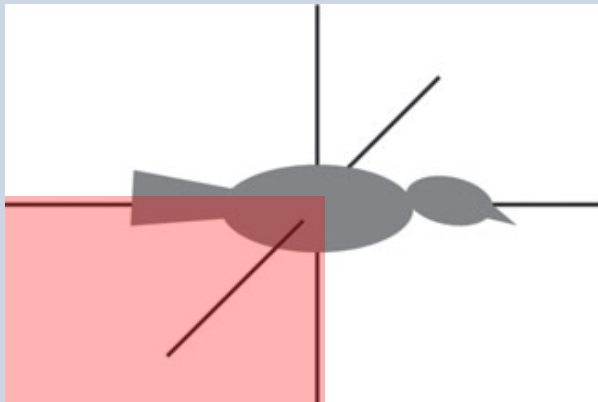
Background

- Estimated **89–340 million** bird-automobile collisions annually in USA
 - 850 times more birds killed by cars than wind turbines
 - Especially important for rare and endangered species



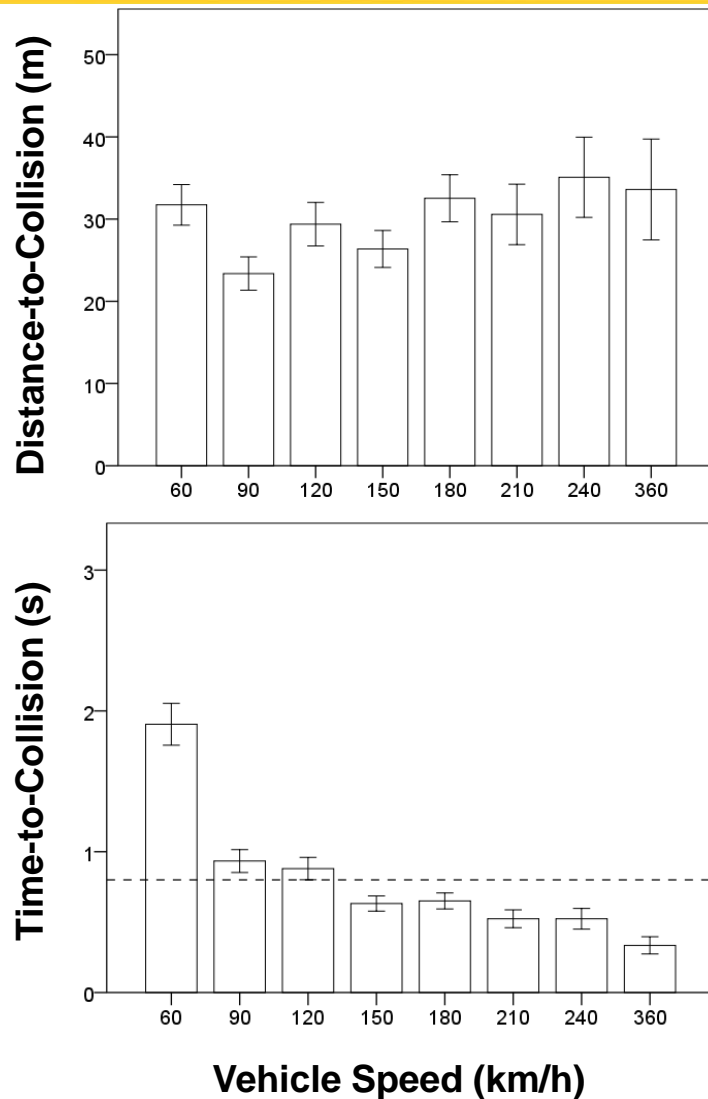
Birds use antipredator behaviors to avoid vehicles

- Necropsies of 92 aircraft-killed birds (32 spp.) from JFKIA
- Injury locations were most frequently posterior and ventral
 - Indicate evasive maneuvers, especially for gulls
 - Birds were not “blindsided”—they tried to react but didn’t have time



Bernhardt et al. 2010. *Ibis* 152:830-834.

How do birds decide when to initiate avoidance?



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Research

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Speed kills: ineffective avian escape responses to oncoming vehicles

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Animal–vehicle collisions cause high levels of vertebrate mortality worldwide, and what goes wrong when animals fail to escape and ultimately collide with vehicles is not well understood. We investigated alert and escape behaviours of captive brown-headed cowbirds (*Molothrus ater*) in response to virtual vehicle approaches of different sizes and at speeds ranging from 60 to 360 km h⁻¹. Alert and flight initiation distances remained similar across vehicle speeds, and accordingly, alert and flight initiation times decreased at higher vehicle speeds. Thus, avoidance behaviours in cowbirds appeared to be based on distance rather than time available for escape, particularly at 60–150 km h⁻¹; however, at higher speeds (more than or equal to 180 km h⁻¹) no trend in response behaviour was discernible. As vehicle speed increased, cowbirds did not have enough time to assess the approaching vehicle, and cowbirds generally did not initiate flight with enough time to avoid collision when vehicle speed exceeded 120 km h⁻¹. Although potentially effective for evading predators, the decision-making process used by cowbirds in our study appears maladaptive in the context of avoiding fast-moving vehicles. Our methodological approach and findings provide a framework to assess how novel management strategies could affect escape rules, and the sensory and cognitive abilities animals use to avoid vehicle collisions.

1. Introduction

When approached by predators and other potential threats, animals must decide when to initiate an escape response. This decision is informed by characteristics of the oncoming object, such as size, speed and directness of approach [1], as well as the state or condition of the animal being threatened, including hunger level, experience and variation in risk-taking behaviours and personalities [2,3]. Animals combine sensory inputs with behavioural rules to assess the costs and benefits of fleeing and thus determine the timing of escape responses [4–6].

Animals appear to react to oncoming automobiles, aircraft and other non-biological threats in a qualitatively similar manner to predators [7,8]. During these encounters, animals use some variation of their antipredator repertoire [9], possibly because the evolutionary novelty of modern vehicles precludes more specialized responses [10]. However, vehicles and natural predators often differ in several important ways, including speed, size and consistency of approach. Such differences can lead to maladaptive (and often fatal) responses when faced with an oncoming vehicle, such as deer ‘freezing’ and turtles withdrawing into their shells while still on the road [10,11].

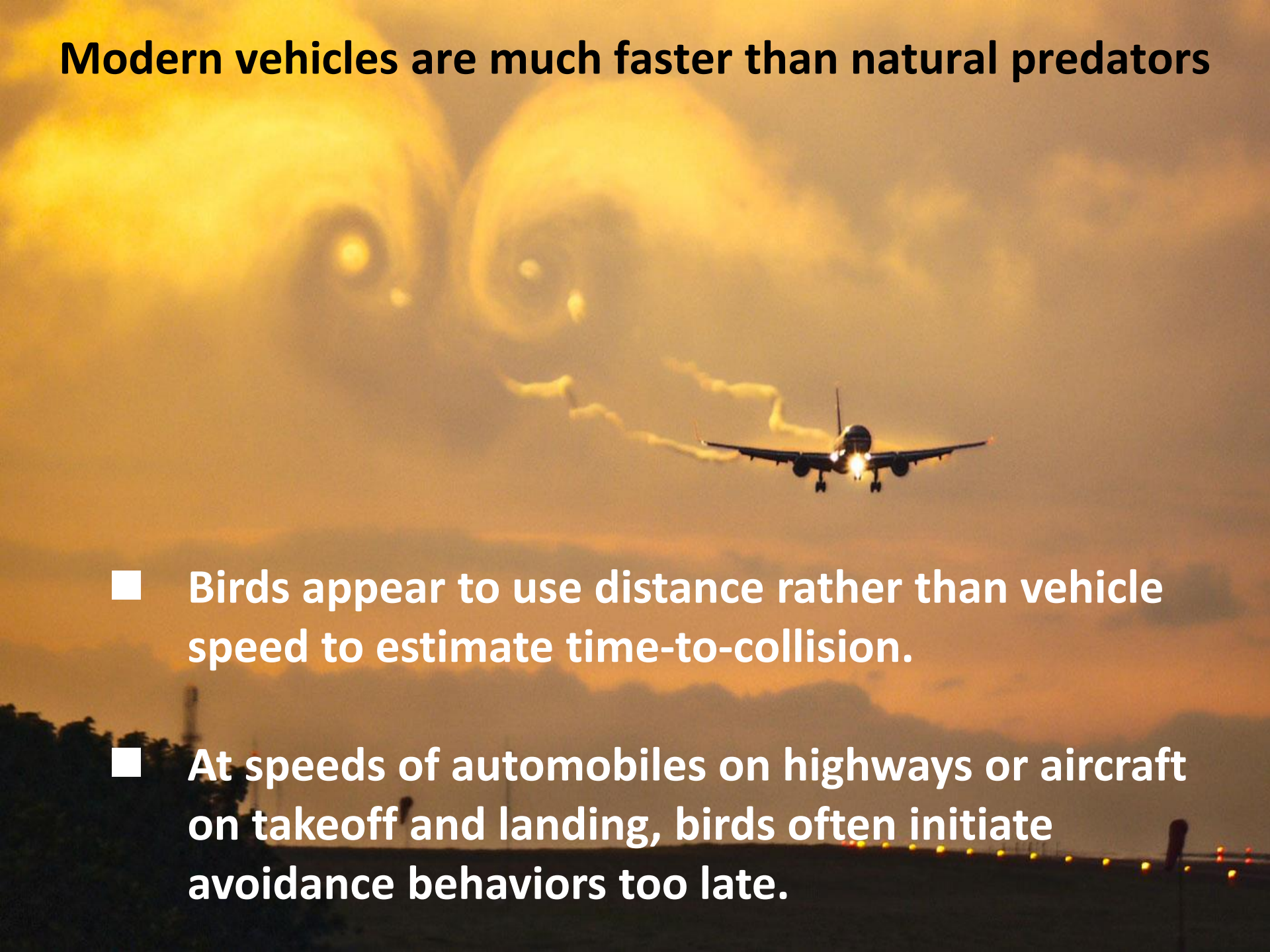
Animal–vehicle collisions, which kill hundreds of millions of birds and other animals each year [12–14], can negatively impact populations [13,16] and pose substantial safety risks to humans [17,18]. Yet, it is unclear what goes wrong when individual animals fail to escape and eventually collide with vehicles [10]. For instance, Tegelström & Ducauze [19] demonstrated that several species of birds escaped earlier from oncoming vehicles as the posted speed limit increased, but the actual speed of vehicles had no effect on escape behaviours. DeVault *et al.* [11] found that near-collisions with turkey vultures (*Coragyps corax*) increased with vehicle speed, suggesting that animals may have difficulty assessing the threat

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DeVault *et al.* 2015.
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Modern vehicles are much faster than natural predators

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- Birds appear to use distance rather than vehicle speed to estimate time-to-collision.
 - At speeds of automobiles on highways or aircraft on takeoff and landing, birds often initiate avoidance behaviors too late.

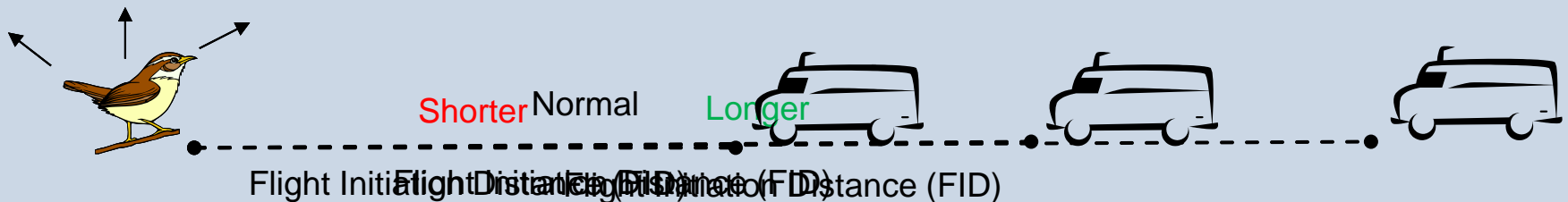
Can birds use experience to mitigate the effects of vehicle speed?

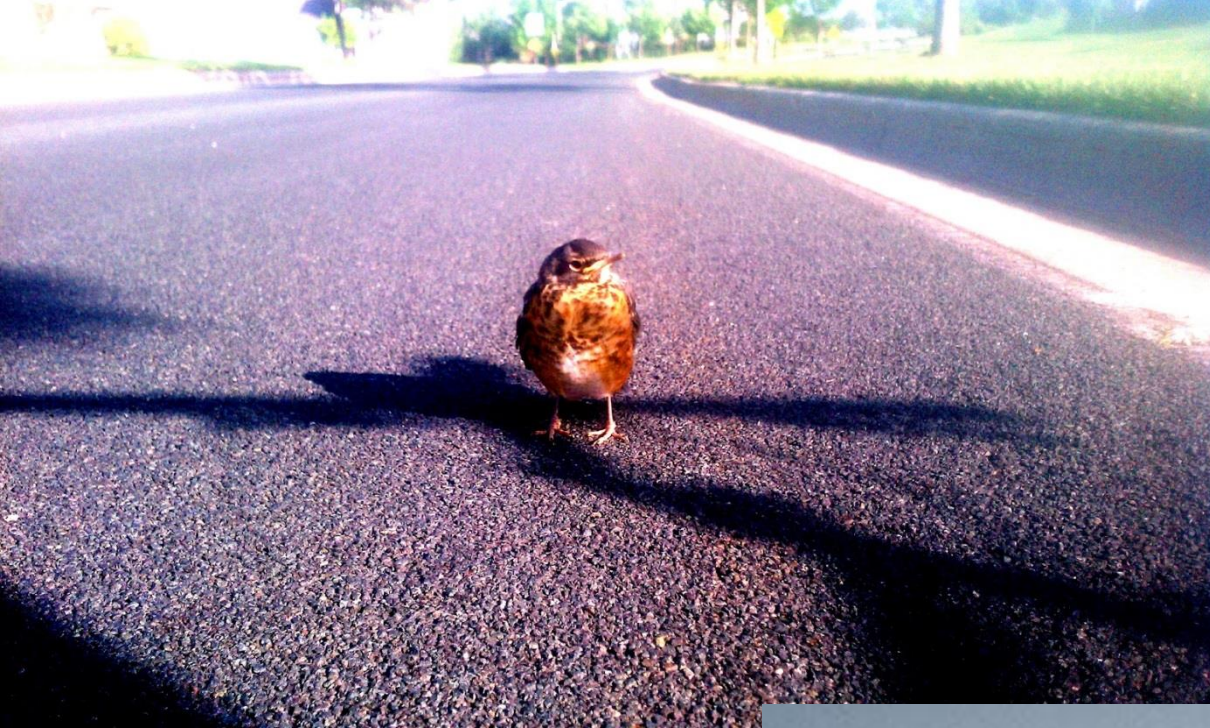
- Across much of the developed world, birds observe many vehicles each day.
 - Cars, aircraft, trains, boats, etc.
- These vehicles don't pursue the birds, but instead travel predictably along roads, flight lines, and railroad tracks.
- How do birds use experience with vehicles to decide on a flight response when a collision is imminent?



Three hypotheses on the role of experience

1. Birds might differentiate between direct and tangential approaches; thus repeated exposure to passing or distant vehicles might have **little effect on FID**.
2. Experienced birds might learn to **increase FID** in response to vehicles over those normally used to escape slower predators, thereby increasing their likelihood of successful avoidance.
3. Experienced birds might habituate to repeated observations of passing or distant vehicles and **decrease FID**, thereby decreasing their likelihood of successful avoidance.





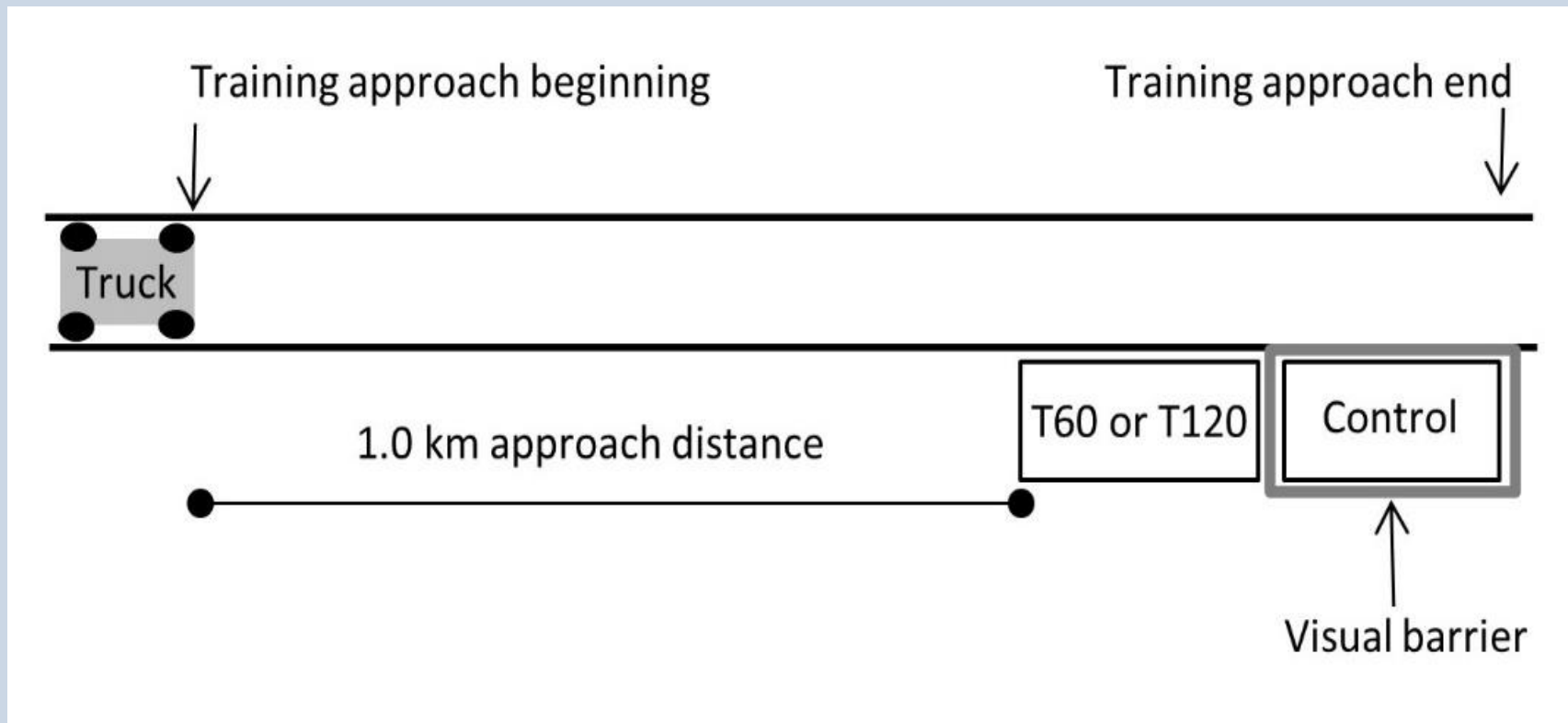
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Methods—Training

- Naïve rock pigeons
 - Birds only saw vehicles we wanted them to see
- 32 vehicle approaches over 4 weeks
- 3 groups of 35 birds each
 1. Trained at 120 km/h
 2. Trained at 60 km/h
 3. Control



Field setup







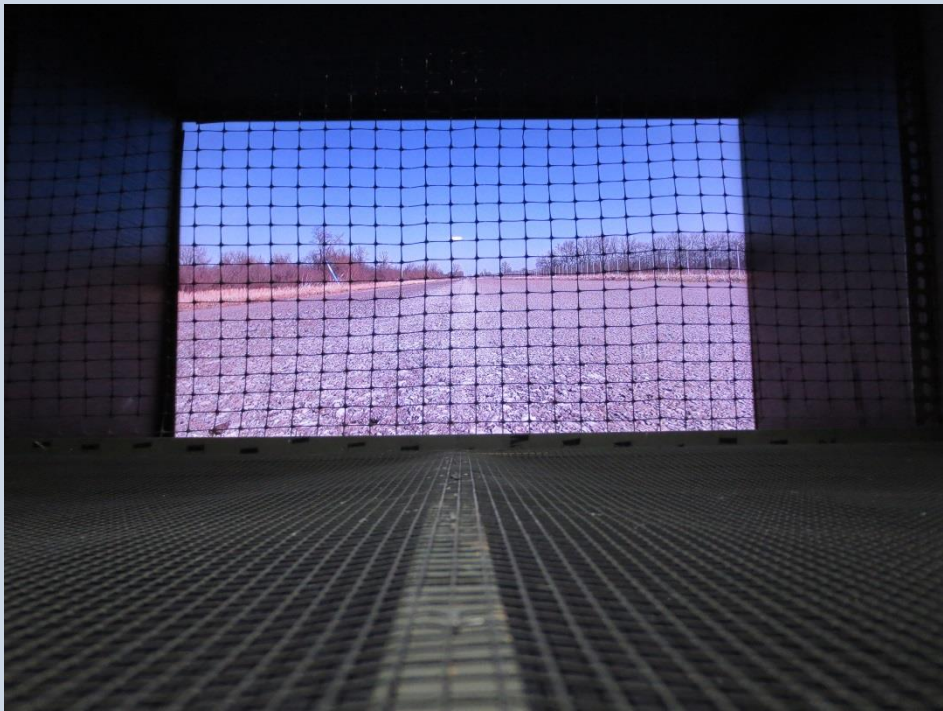


Methods—Measuring FID

- Video lab
 - Allowed simulation of head-on approaches
 - Allowed high-speed approaches
- 1 km vehicle approach at 120 or 240 km/h
 - 30 birds from each training group tested, one at a time
 - Visual only
- Recorded behavior with 4 cameras
- Quantified FID to nearest 1/15 sec









Analyses

- General Linear Model
- DV = FID (square-root transformed)
- IVs = training group (T120, T60, control), virtual vehicle approach speed (120, 240 km/h), interaction
- Post-hoc analysis with LSD tests

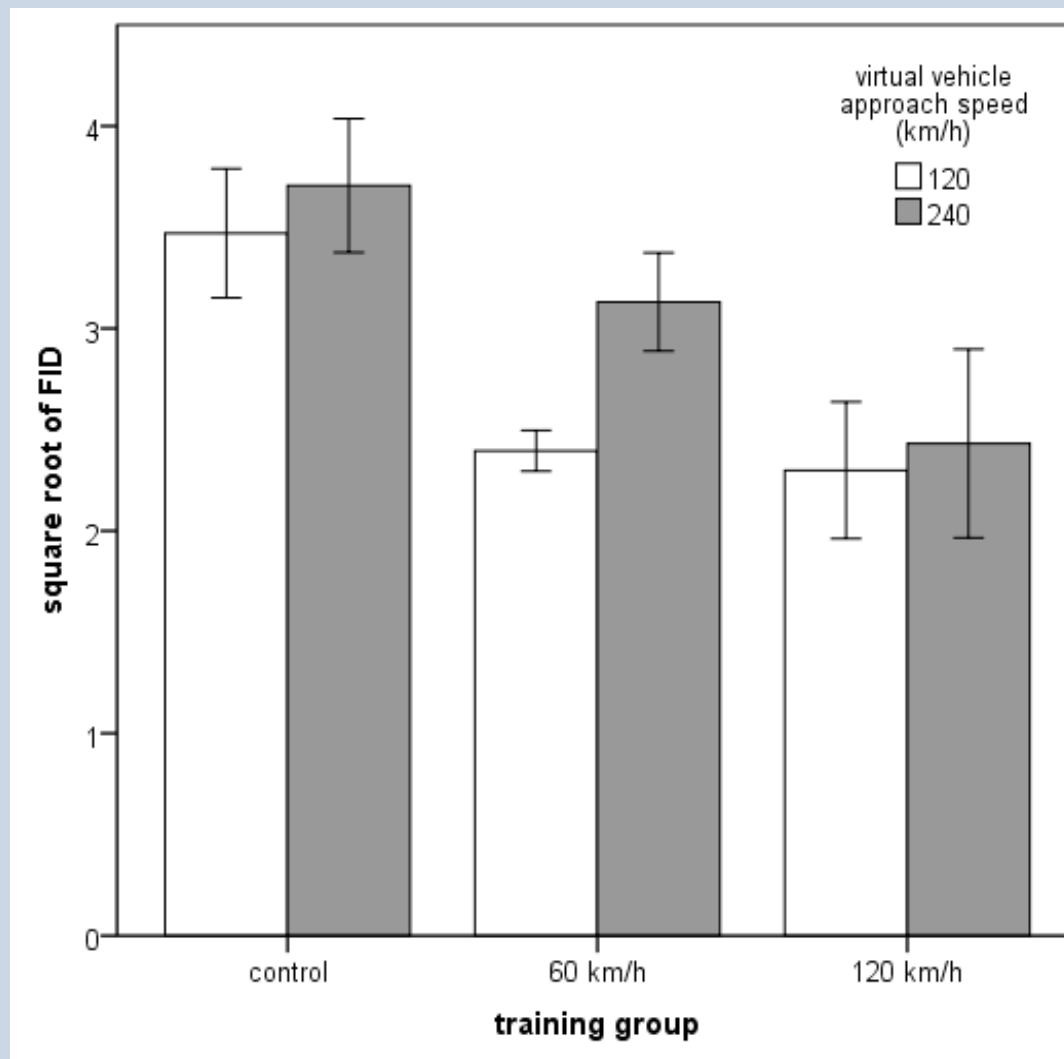
Results

- Pigeons showed very little reaction to vehicle approach during training
- During video playback, avoidance response evident in 83 of 90 virtual vehicle approaches
- Training group: $P = 0.001$
 - Naïve (control) group had longer FID than T60 or T120 groups
 - No difference ($P = 0.217$) between T60 and T120 groups
- Virtual vehicle approach speed ($P = 0.162$) and interaction ($P = 0.602$) nonsignificant

Results

Training group	Virtual vehicle approach speed	Mean (m)	SD (m)
Control	120 km/h	13.46	10.47
	240 km/h	15.27	9.84
T60 (60 km/h)	120 km/h	5.88	1.98
	240 km/h	10.63	5.70
T120 (120 km/h)	120 km/h	6.89	4.67
	240 km/h	8.96	9.00

Results



Primary finding

- Inexperienced birds had longer FIDs in response to direct vehicle approach than experienced birds
 - Experienced birds evidently learned that vehicles do not pose a threat
 - Habituation?

Conclusions

- Habituation could contribute to many bird-vehicle collisions
 - Resident raptors on airfields?



Questions or comments?

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